

# The Baikal-GVD Neutrino Telescope: Muon Track Events Reconstruction



BAIKAL-GVD

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BAIKAL-GVD

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# Introduction

- First full-scale cluster “Dubna” was commissioned and taking data since 2016
- In 2019, 5 clusters working = 40 strings = 1440 OM<sub>s</sub> = 0.25 km<sup>3</sup>
- Charge and Time calibrations performed and applied
- Real position of every OM measured with Acoustic Positioning System
- Lake and PMT noise studied in detail.
- Data quality monitoring
- Muon track reconstruction developed using 2016 data

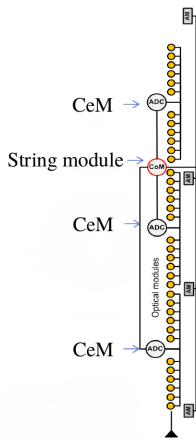




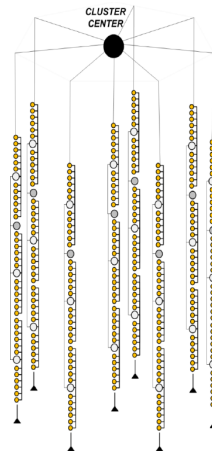
# Baikal-GVD



Optical Module (OM)  
PMT: Hamamatsu R7081-100



String: 3 sections, 12 OMs/section  
Instrumented depth: 750 -1250 m



Cluster: 8 strings, 288 OMs  
Radius 60 m, Clusters distance 300 m

# Track Reconstruction Procedure

**Track Parametrization:** At least 6 hits at 3 strings are required, simple  $\chi^2$ -like fit is used so far

$$\vec{R}(t) = \vec{R}_0 + c(t - t_0)\vec{V} \quad (1)$$

where  $\vec{V}$  is a unit vector and  $\vec{R}_0$  and  $t_0$  are taken in plane  $z = 0$ .

**Initial Track Approximation:**

$$\vec{V}_{init} = \frac{1}{\sum_{t_i < t_j} |\vec{R}_{ij}|} \sum_{t_i < t_j} \vec{R}_{ij} \quad (2)$$

where  $i$  and  $j$  are ordered in time and belong to different strings.

**Minimization function (quality):**

$$Q = \sum_{i=1}^{N_{hit}} \left[ \frac{(t_i^{est} - t_i)^2}{\sigma^2} + \frac{A(a_i)D(d_i)}{d_0} \right] \quad (3)$$

where  $A$  and  $D$  are amplitude and distance functions and  $\sigma_t = 3$  ns. Inspired by ANTARES arxiv:1105.4116.

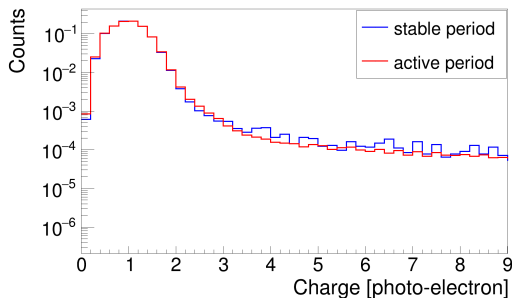
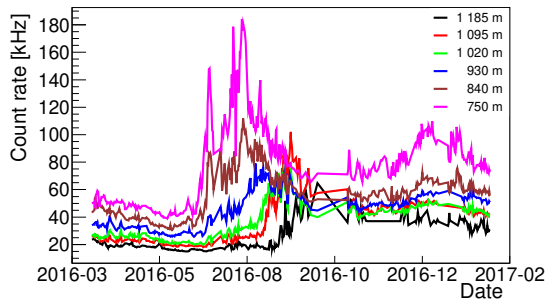
Muon prompt Cherenkov radiation approximation is used for the time estimation

# Lake and Detector Noise

OM pulses due to PMT dark current and lake fauna must be rejected before reconstruction

Noise rate 20-60 kHz for “low noise period” → Signal at photoelectron level

Event frame: 5  $\mu$ s : 60 noise pulses per event



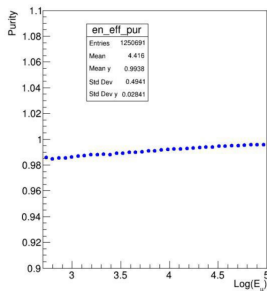
# Noise Suppression

Pulses are clustered around “seed”:  $Q > 2$  p.e.  
Each causally-connected pulse with  $Q > 0.5$  p.e. is clustered

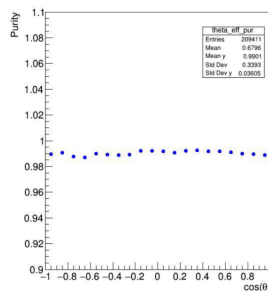
## Causality

$$|t_i - t_j| \leq \frac{\Delta R_{ij}}{c_w} + t_s, \quad t_s = 10 \text{ ns} \quad (4)$$

Initial track approximation is calculated, outliers are removed iteratively in tightening set of cuts  
Cluster of pulses with the best quality is selected

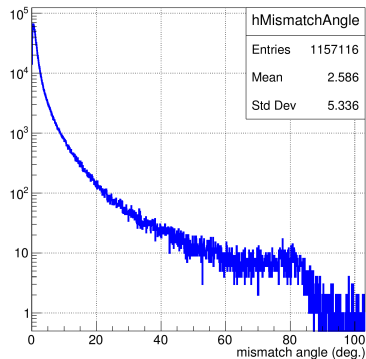


Purity of selected group of pulses  $\sim 99\%$   
weakly depends on muon incident angle  
and energy

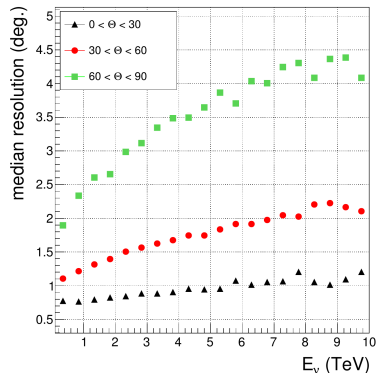


# Reconstruction Performance

Reconstruction performance is evaluated on atmospheric neutrino sample,  $E > 100$  GeV



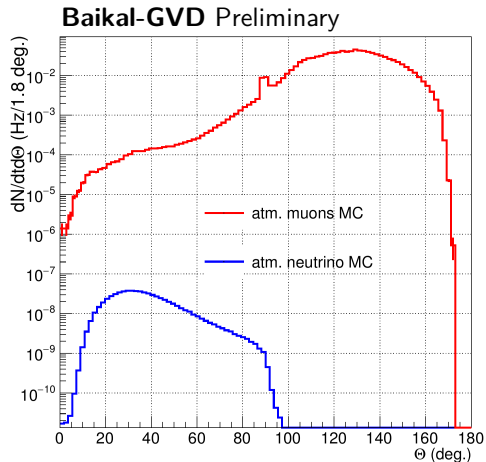
median:  $\sim 1.2$  deg  
tail > 10 deg: 4.4 %  
tail > 20 deg: 1.4 %



Degrades with energy  
Worse for horizontal events

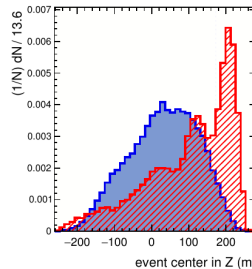
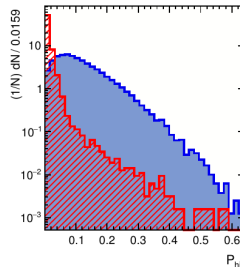
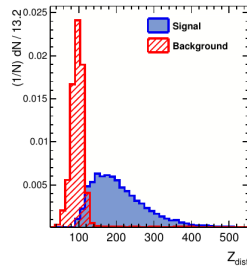
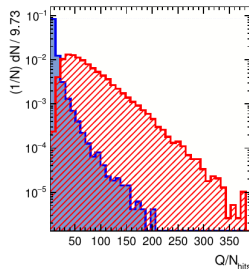
# Atmospheric Muon Flux

- Large tail of atmospheric muons misreconstructed as up-going events ( $\sim 3\%$ )
- $\sim 4$ -5 orders of magnitude larger than expected up-going neutrino flux
- Technique to reject misreconstructed muon groups is needed
- Simplest: track quality variable cuts, but rejects a lot of signal
- Boosted decision trees: acceptable signal efficiency

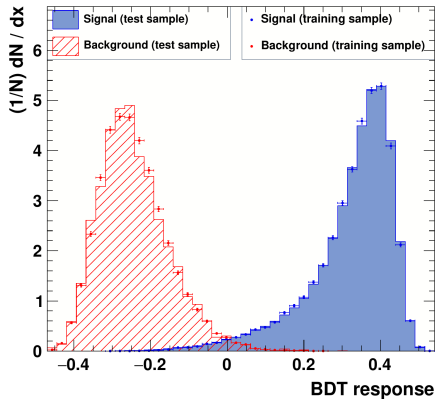


# Selection of up-going tracks

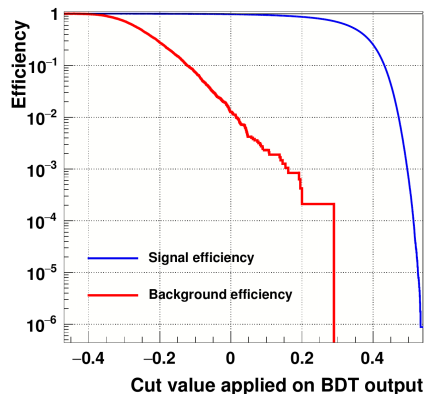
- TMVA framework from ROOT package was used to train the BDT
- A set of 15 quality variables was used at input
- Most significant ones:
  - ▶  $Quality/N_{hits}$
  - ▶  $P_{hit}$ : probability of given hit collection
  - ▶  $Z_{dist}$ : max distance between OM projections on the track
  - ▶ Event center in  $Z$  weighted with pulse charge
- **Signal sample: up-going neutrino  $E > 100$  GeV**
- **Background sample: misreconstructed down-going muon groups,  $\theta_{rec} < 80$  deg**



# BDT performance



Cut	$S_{eff}$ [%]
0.25	80
0.3	70
0.35	50
0.4	25



Background is suppressed at the level of  $10^4 - 10^5$ ,  
maintaining signal efficiency at the level of  $\sim 80\%$  (cut 0.25)

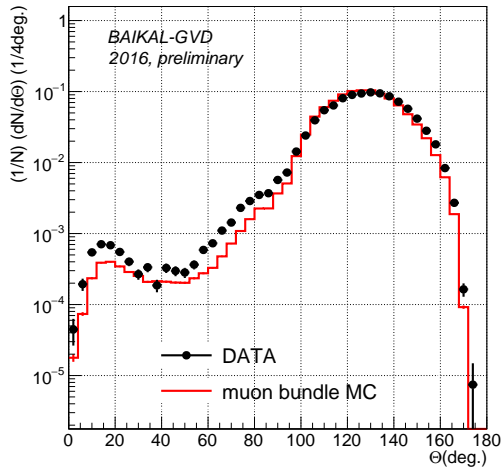


# Data/MC comparison

## "Good dataset" (15 days of exposition):

- "Low noise period": runs 90 - 200
- Fixed configuration: 3 sections are off (12.5 % of the cluster off)
- Events with active LED's are rejected

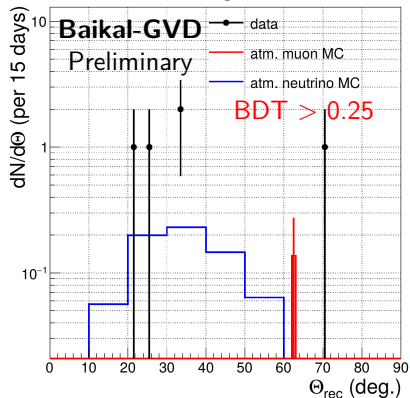
**Total 6/3 muon rate in data: 0.22 Hz**  
**Rate in MC is 32 % lower**



# Results

Good dataset (15 days exposition)

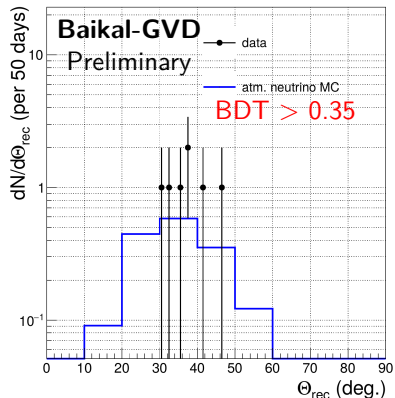
fixed configuration



bckg. expected	0.14
signal expected	0.72
data	5

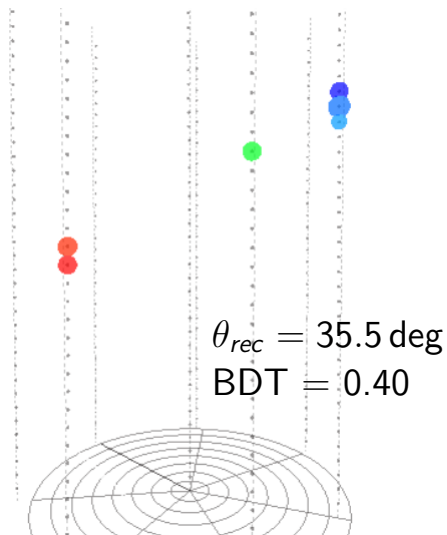
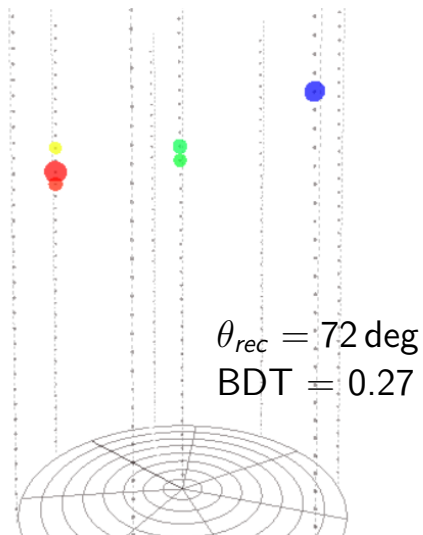
50 days exposition

all configurations, noisy runs, hard BDT cut

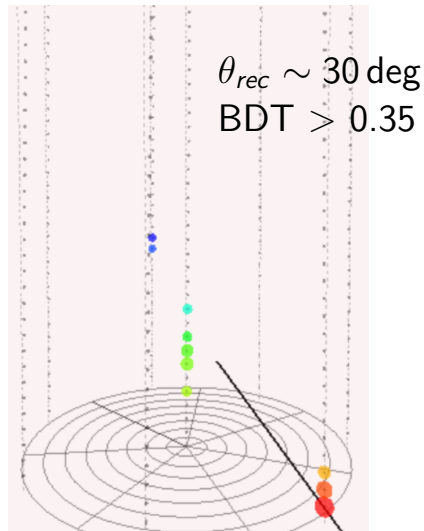
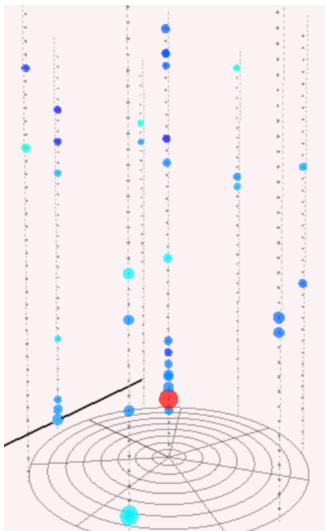


bckg. expected	—
signal expected	1.6
data	7

# Event Display



# Event Display



# Summary

Detector properties for 2016 cluster have been studied

We continue to improve MC to match with detector conditions

Procedures to certify good data are being developed

Track reconstruction software has been developed

Simple  $\chi^2$ -like fit

Atmospheric background rejection procedure has been developed

Background rejection at the level of  $10^4 - 10^5$

Preliminary results on atmospheric neutrino flux are available

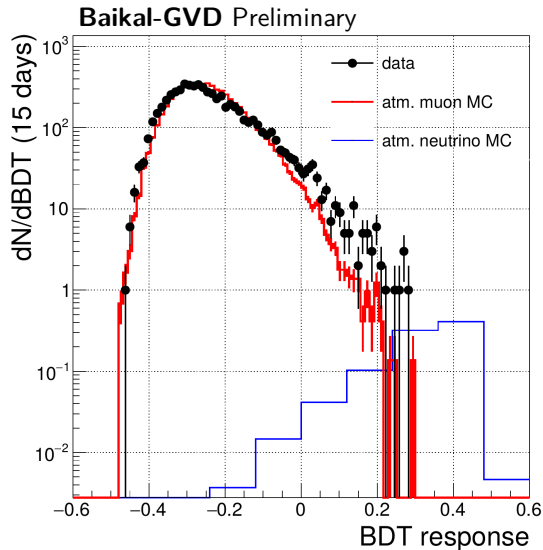
1 neutrino candidate per  $\sim 3$  days per cluster with the current technique

Working hard on the implementation of the likelihood approach

A large crane is positioned on a frozen lake at night. The crane's boom is extended upwards, and its base is on the ice. In the foreground, there are several large, white ice blocks. To the left of the crane, there is a line of orange buoys. The background shows a dark, starry sky and distant mountains. The text "Thank you for your attention." is overlaid in the center of the image.

Thank you for your attention.

# Results



**BDT for "Good dataset":**

MC background is scaled by the factor 3.58 to match the data normalization

**BDT  $> 0.25$  cut is used for neutrino selection**

# Detector Effective Areas

